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Harmonic Domain<br>
Leonardo A. A. Souza<sup>1,2</sup>, Antonio C. S. Lima<sup>2</sup>, Marcelo B. Martins<sup>1</sup>,<br>
and Marcus V. Viegas<sup>1</sup> **METROLOGIA**<br> **Transducers I/O modeling by ANN based on**<br> **Domain**<br> **Leonardo A. A. Souza<sup>12</sup>, Antonio C. S. Lima<sup>2</sup>, Marcelo B. Martins<sup>1</sup>,<br>
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Cavisa, 25250**r transducers I/O modeling by ANN based on**<br> **2. Domain**<br> **Leonardo A. A. Souza<sup>12</sup>, Antonio C. S. Lima<sup>2</sup>, Marcelo B. Martins<sup>1</sup>,<br>
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<sup>1</sup> Instituto Nacional de Metrologia, Qualidade e Tecnologia (INMETRO), Duque de<br>
<sup>2</sup> Instituto Nacion Example 16.**<br> **Leonardo A. A. Souza<sup>1,2</sup>, Antonio C. S. Lima<sup>2</sup>, Marcelo B. Martins<sup>1</sup>,<br>
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Caxias, 25250-020, Brasil<br>
<sup>2</sup> Universid introduce considerable harmonic states.** The states of the considerable transducers and the function in the grid [1]. Meanwhile, voltage and current transducers in the languard in the languard in the presents and the prop

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12. Abstratt. Modeling the non-linearity of transduce <sup>2</sup> Universidade Federal do Rio de Janeiro (COPPE/UFRJ), Rio de Janeiro, 21941-972,<br>
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Hassouza@inmetro.gov.br<br> **Abstract**. Modeling the non-linearity of transducers such as inductive voltage transformers is<br>
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Abstract. Modeling the non-linearity of transducers such as inductive voltage transformers is<br>
challenging for metrologists. This paper presents a methodology to model non-linear<br>
transduce Interto.gov.br<br> **Abstract**. Modeling the non-linearity of transducers such as inductive voltage transformers is<br>
challenging for metrologists. This paper presents a methodology to motel non-linear<br>
transducers through a bl **Abstract.** Modeling the non-linearity of transducers such as inductive voltage transformal<br>alternation compensations and the bost-bost approach. First, input and undput signals are decomposed<br>harmonic components, to be ma **Abstract Modeling the non-linearity of transducer such as inductive voltage transformation chiral change in contage through a blackbox approach First, input and output signals are decomposed involvements through a halach** challenging for metrologies. This paper presents a methodology to model non-linear transmission in the harmonic components, to be mapped by an appropriat Artificial Neural Network (ANN). To support the choice of the ANN ge Iransducers through a black-host approach. First, imput and ougtu signals are decomposed into the origin of the considered of the ANN general features, we perform simulations in the Harmonic interactions that the uncertain harmonic components, to be mapped by an appropriate Artificial Neural Network (ANN, To<br>
be procedure, which different harmonic interactions due to non-linearity effects are considered by<br>
the procedure, which different har

support architect architecture and training we perform simulations in the Hamonic Domain (HD). That way, harmonic intertesting or multi-one approaches. The proposed methodology is then used to the practice simulations cons by the procedure, which and the procedure, which and the procedure, which and the methodical performance of one-interactions of the procedure. The methodical performance of one voltage transformer submitted to multi-harmon in the procedure is can controlled to the Harmonic Signals.<br>
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2. The rise of distributed generation and the increase of non-linear loads i in a typical multi-harmonic signals.<br>
In the maximum scenario of the method in the principal maximum control and the method in the single of the method or originally designed to operate in a typical singuoidal scenario, ar 1. Introduction<br>The rise of distributed generation and the inercase of non-linear loads in power systems progressively<br>thirtoduce considerable harmonic distortion in the grid [1]. Meanwhile, voltage and current transducers



2. Non-linearity representation in Harmonic Domain<br>
For a mathematical representation of nonlinear systems, the typical analysis performed with Fourier<br>
Series components ignores an important characteristic resulting from **For a mathematical representation in Harmonic Domain**<br>For a mathematical representation of nonlinear systems, the typical analysis performed with Fourier<br>Series components ignores an important tharacteristic resulting fr **Example 2.**<br>Series components ignores an important characteristic resulting from the non-linearity representation of nonlinear systems, the typical analysis performed with Fourier Series components ignores an important ch **Electrical equipment: Consider the coupling of distinct frequency**  $\overline{2025}$ <br>
For a mathematical representation of nonlinear systems, the typical analysis performed with Fourier<br>
Series components ignores an importan 2. Non-linearity representation in Harmonic Domain<br>For a mathematical representation of nonlinear systems, the typical analysis performed with Fourier-<br>Series components ignores an important characteristic resulting from 2. Non-linearity representation in Harmonic Domain<br>
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Series components ignores an important characteristic resulting fr 2. **Non-linearity representation in Harmonic Domain**<br>
For a mathematical representation of nonlinear systems, the typical analysis performed with Fourier<br>
For a mathematical representation of nonlinear systems, the typica

$$
x(t) = \sum_{i=-h}^{h} X_h e^{jh\omega_0 t} \Rightarrow \mathbf{X} \tag{1}
$$

As input data, we consider the harmonic components of the transducer input signals. The transducer input signals of a harmonic function in equation (1) represent the input signal, also represented in the HD.<br>
Let the harm proposar menonongy to rango narmonic compunes, we implemented an argormant or carculating, in<br>the HD, the output signals of a known transducer, from its input signal of a nonlinear transducer.<br>Let the harmonic function in the rin, the output signals of a known transfactor; from its input signal, also represented in the rin.<br>
Let the harmonic function in equation (1) represent the input signal of a nonlinear transducer.<br>
The HD vector form The HD vector form of  $x(t)$  is represented by **X**, composed by tis respective coefficients of the proposent an series. Each coefficient is related to the order of the associated harmonic apponent. In the same way,  $y(t)$  r The HD vector form of  $x(t)$  is represented by **X**, composed by its respective coefficient<br>complex exponential series. Each coefficient is related to the order of the associated ha<br>component. In the same way,  $y(t)$  represe

$$
y(t) = \sum_{q=0}^{n} b_q x^q(t) \quad , \tag{2}
$$

$$
\mathbf{X}^q = \mathbf{X}^{q-2} \circledast \mathbf{X}^{q-1} \quad , \tag{3}
$$

scape exponent series. racer to moreover is velocated with a single end of the mapping temporal of the same way,  $y(t)$  represents the output signal, and is HD vector form is represented<br>
The transducer is modeled by a non However, in the same way,  $y(t)$  represents the otappar aggins, and its HD cetar form is represented.<br>The transducer is modeled by a nonlinear polynomial function in equation (2) where q is the pyomial order, and  $b_t$  is t of the transducer is modeled by a nonlinear polynomial function in equation (2) where q is the polynomial order, and  $b_q$  is the respective coefficient.<br>  $y(t) = \sum_{q=0}^{n} b_q x^q(t)$ , (2)<br>
As input data, we consider the harmon The mass of interest of interest of interest of interest of interest of interest applied waveform.<br>
As imput data, we consider the harmonic components of the transducer input signals. The output<br>
As imput data, we conside Magnitude of each harmonic volume of the transdact the harmonic components of the transdacer input signals. The output<br>data is given by the HD calculation algorithm. According to [3], the polynomial valuation via<br>data is  $y(t) = \sum_{q=0}^{n} h_q x^q(t)$ , (2)<br>
As input data, we consider the harmonic components of the transducer input signals. The output<br>
data is given by the HD calculation algorithm. According to [3], the polynomial evaluation via<br>  $y(t) = \sum_{q=0} b_q x^q(t)$ , (2)<br>
As input data, we consider the harmonic components of the transducer input signals. The output<br>
data is given by the HD calculation algorithm. According to [3], the polynomial evaluation via<br>
re **EVALUAT THEST AS STAGE AT STAGE AT STAGE AT STAGE ANTIFICIALLY AND THE STAGE AND SERVIDENT ART AND STAGE AND SERVIDENT ASSESS THE STAGE AND SERVIDENT ASSESS THE ANNOUNCIONS, given by**  $\mathbf{X}^q = \mathbf{X}^{q-2} \otimes \mathbf{X}^{q-1}$ **,** As input data, we consider the harmonic components of the transducer input signals. The output<br>data is given by the HD calculation algorithm. According to [3], the polynomial evaluation via<br>repeated convolutions, given by As input data, we consider the harmonic components of the transducer input signals. The output<br>data is given by the HD calculation algorithm. According to [3], the polynomial evaluation via<br>repeated convolutions, given by as is given by the HD calculation algorithm. According to [3], the polynomial evaluation via<br>stated convolutions, given by<br> $\mathbf{X}^q = \mathbf{X}^{q-2} \circledast \mathbf{X}^{q-1}$ , (3)<br>is an appropriate tool to represent non-linearities in repeated convolutions, given by<br>  $\mathbf{X}^q = \mathbf{X}^{q-2} \oplus \mathbf{X}^{q-1}$ , (3)<br>
is an appropriate tool to represent non-linearities in IID, being able to take into account harmonic<br>
interactions between components.<br>
3. *I/O*  $X^q = X^{q-2} \otimes X^{q-1}$ , (3)<br>is an appropriate tool to represent non-linearities in HD, being able to take into account harmonic<br>interactions between components.<br>J. *I/O* non-linear mapping investigation using HD<br>In order t



layer composition, neurons with *sigmoid* activation functions were used, as shown in the schematic diagram presented in figure 1 (Flux 1). First, part of the *dataset* is used to perform the supervised training. Several t diagram presented in figure 1 (Flux 1). First, part of the dataset is used, as shown in the schematic diagram presented in figure 1 (Flux 1). First, part of the *dataset* is used to perform the supervised training. Several the memoriton, neurons with *sigmoid* activation functions were used, as shown in the schematic diagram presented in figure 1 (Flux 1). First, part of the *dataset* is used to perform the supervised training. Several train the most suitable results for the *sigmoid* activation functions were used, as shown in the schematic diagram presented in figure 1 (Flux 1). First, part of the *dataset* is used to perform the supervised training. Several Model outputs showed differences between the ratio of each harmonic components lower than few differences between the ratio of each harmonic components lower than few model outputs showed differences between the ratio of parts-per-million.



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Figure 1. Schematic diagram presenting the two ANN training processes.<br>
ANN **implementation** for real measurements<br>
or everywing out the general investigation on the actriticeture seement in figure 1. Schematic diagram presenting the two ANN training processes.<br>
4. ANN implementation for real measurements<br>
After carrying out the general investigation on the architecture of the ANNs in the previous s **EXECUTE: EXECUTE: Examplementation for real measurements**<br>**4. ANN implementation for real measurements**<br>**4. ANN implementation for real measurements** of the ANNs in the previous section,<br>After carrying out the general investigation on the Figure 1. Schematic diagram presenting the two ANN training processes.<br> **4.** ANN implementation for real measurements<br>
After carrying out the general investigation on the architecture of the ANNs in the previous section,<br> **4. ANN implementation for real measurements**<br>**4. ANN implementation for real measurements**<br>After carrying out the general investigation on the architecture of the ANNs in the previous section,<br>we implemented the method u







**Prefigred a** 1.0004<br> **Examplementary results in the final method is a promising alternative to deal with multi-<br>
Fig. 3. Relative ratio comparison for the fundamental component measured under different<br>
<b>Examplementary r** ANN adherence. However, some issues regarding synchronized I/O measurements in higher frequency<br>
The stationary of the fundamental component measured under different<br>
Sections<br>
The obtained results suggest that the propos **Example 1.0022**<br> **Example 1.0022**<br> **Example 1.0022**<br> **Example 1.0022**<br> **Example 1.0022**<br> **Example 1.0021**<br> **Example 1.0018 in a methodic of the fundamental component measured under different<br>
<b>Example 1.0021**<br> **Example 1** 



# References

- Far as an estimation of the ANN model<sup>'</sup>s contribution of the method's performance is necessary, as<br>far as an estimation of the ANN model's contribution to the overall uncertainty.<br>**References**<br>[1] M. Faifer et al., "Overc Fair the method of the method's performance is necessary, as<br>far as an estimation of the ANN model's contribution to the overall uncertainty.<br>**References**<br>[1] M. Faifer et al., "Overcoming Frequency Response Measurements o Frequency ranges. Finally, a thorough evaluation of the method's performance is necessary, as<br>estimation of the ANN model's contribution to the overall uncertainty.<br>Faifer et al., "Overcoming Frequency Response Measurement Frequency ranges. Finally, a thorough evaluation of the method's performance is necessary, as<br>
stimation of the ANN model's contribution to the overall uncertainty.<br> **Example 1800-2807, and the SNN** model's contribution to FRICULT CONTINUITY of the method's performance is necessary, as<br>far as an estimation of the ANN model's contribution to the overall uncertainty.<br>
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[1] M. Faifer et al., "Overcoming Frequency Response Measurement Frequency ranges. Finally, a thorough evaluation of the method's performance is necessary, as<br>stimation of the ANN model's contribution to the overall uncertainty.<br> **Example 18.** "Overcoming Frequency Response Measurements **EXECTS AN ACHA, THE SET ACHA, THE SET ACHA, THE SET ACHA, THE SET AND THE SET ACHA, THE SET ACHA, THE SET AND AN EXECTS AND AN ACHADEM THE SET AND AN ENTERT AT A provach Based on Quasi-Sinusoidal Voltera Models", in IEEE** The Math Works, 2001.<br>
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Rer as an estimation of the ANN model's contribution to the overall uncertainty.<br>
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